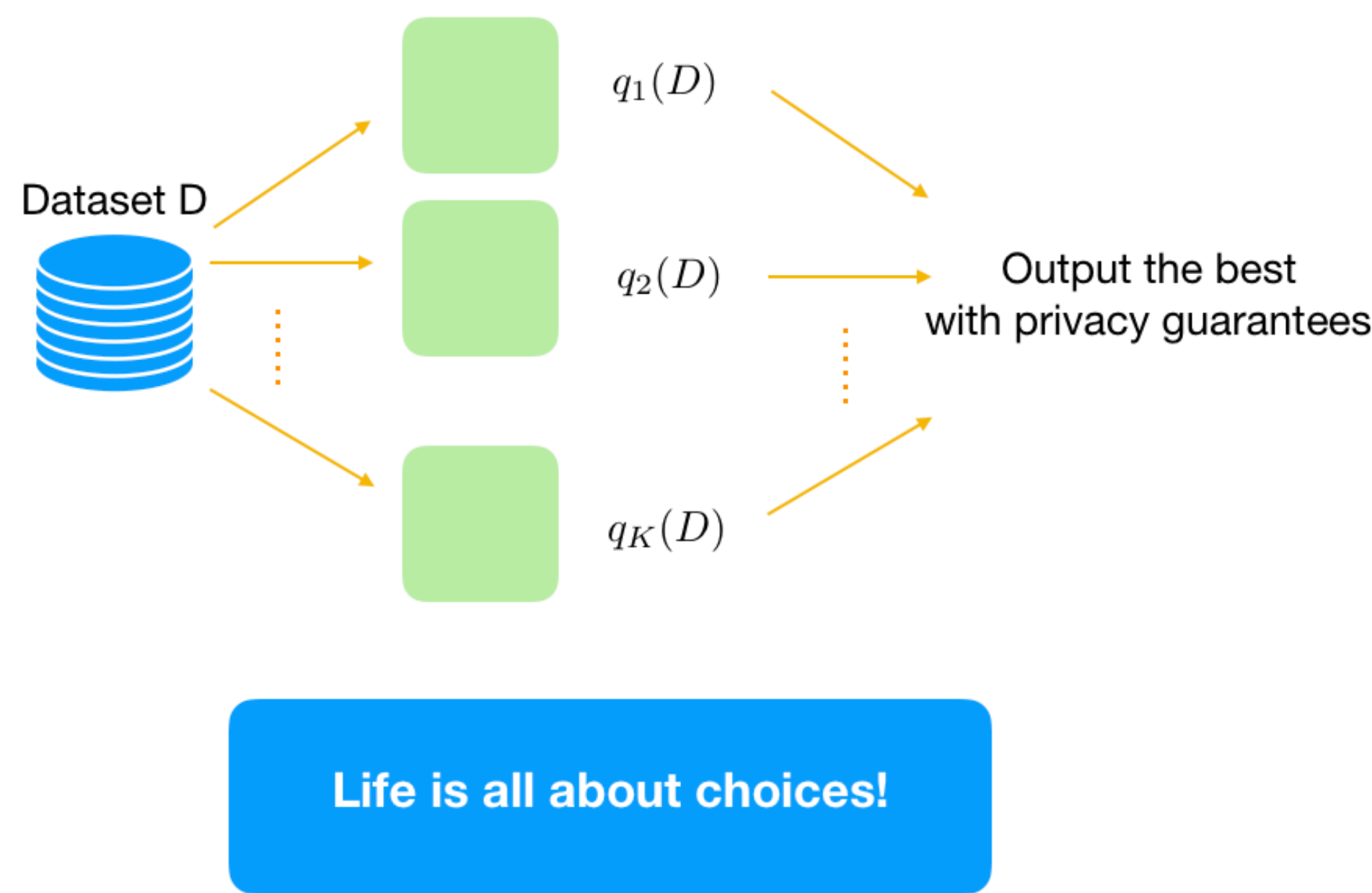


Private Selection from Private Candidates

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Private Selection



Differential privacy (DP)

(by Dwork, McSherry, Nissim, Smith)

Whether you are in the data set or not, it makes little difference

Let $\mathcal{M} : \mathcal{D}^n \rightarrow \mathcal{R}$ be a randomized algorithm

We say that \mathcal{M} satisfies (ϵ, δ) -DP if $\forall D, D'$ s.t. $|D - D'| \leq 1, \forall S$

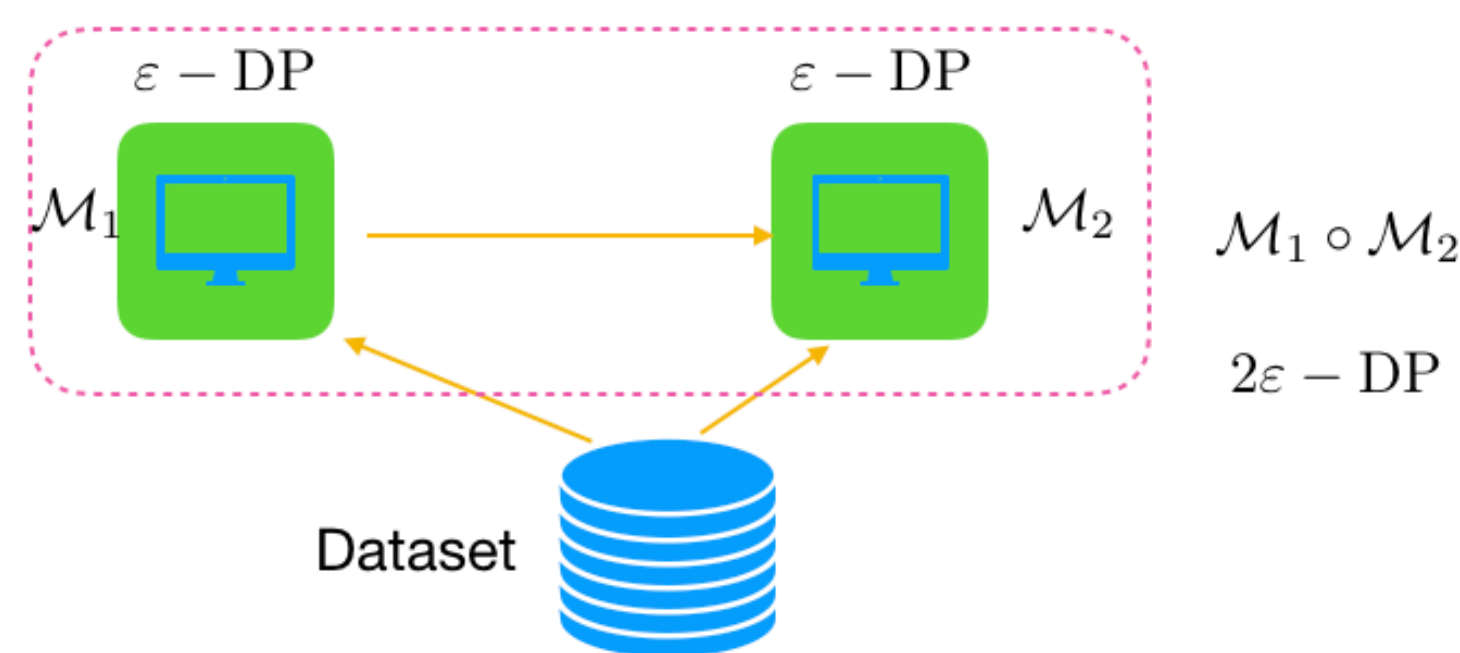
$$\Pr[\mathcal{M}(D) \in S] \leq \exp(\epsilon) \cdot \Pr[\mathcal{M}(D') \in S] + \delta.$$

If $\delta = 0$, we say that \mathcal{M} satisfies ϵ -DP

Composition Theorems

$$\Pr[\mathcal{M}(D) \in S] \leq e^\epsilon \cdot \Pr[\mathcal{M}(D') \in S]$$

- Basic composition



K-fold composition: $(K\epsilon)$ -DP

- Advanced composition: $(\sqrt{2K \ln \frac{1}{\delta}} \cdot \epsilon + 2k\epsilon^2, \delta)$ -DP

Private Selection for Lipschitz Functions

Exponential mechanism [McSherry, Talwar]

If $\forall i, q_i(D)$ is $1/\epsilon$ -Lipschitz: $|q_i(D) - q_i(D')| \leq 1/\epsilon$

$$\max\{q_i(D) + \text{Lap}(1/\epsilon)\} \text{ is } \epsilon\text{-DP}$$

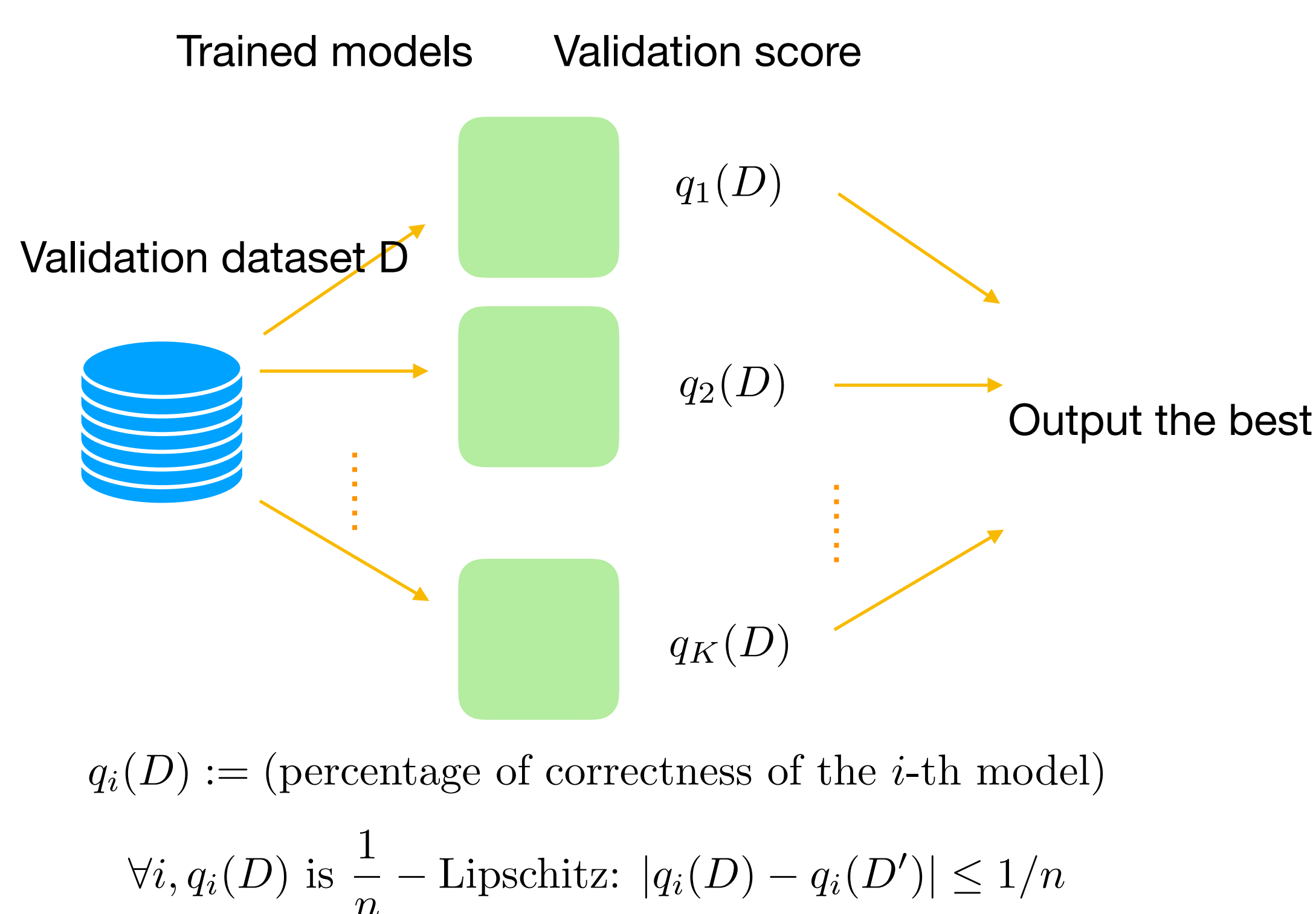
Privacy

Moreover, if the index j is the maximizer, then

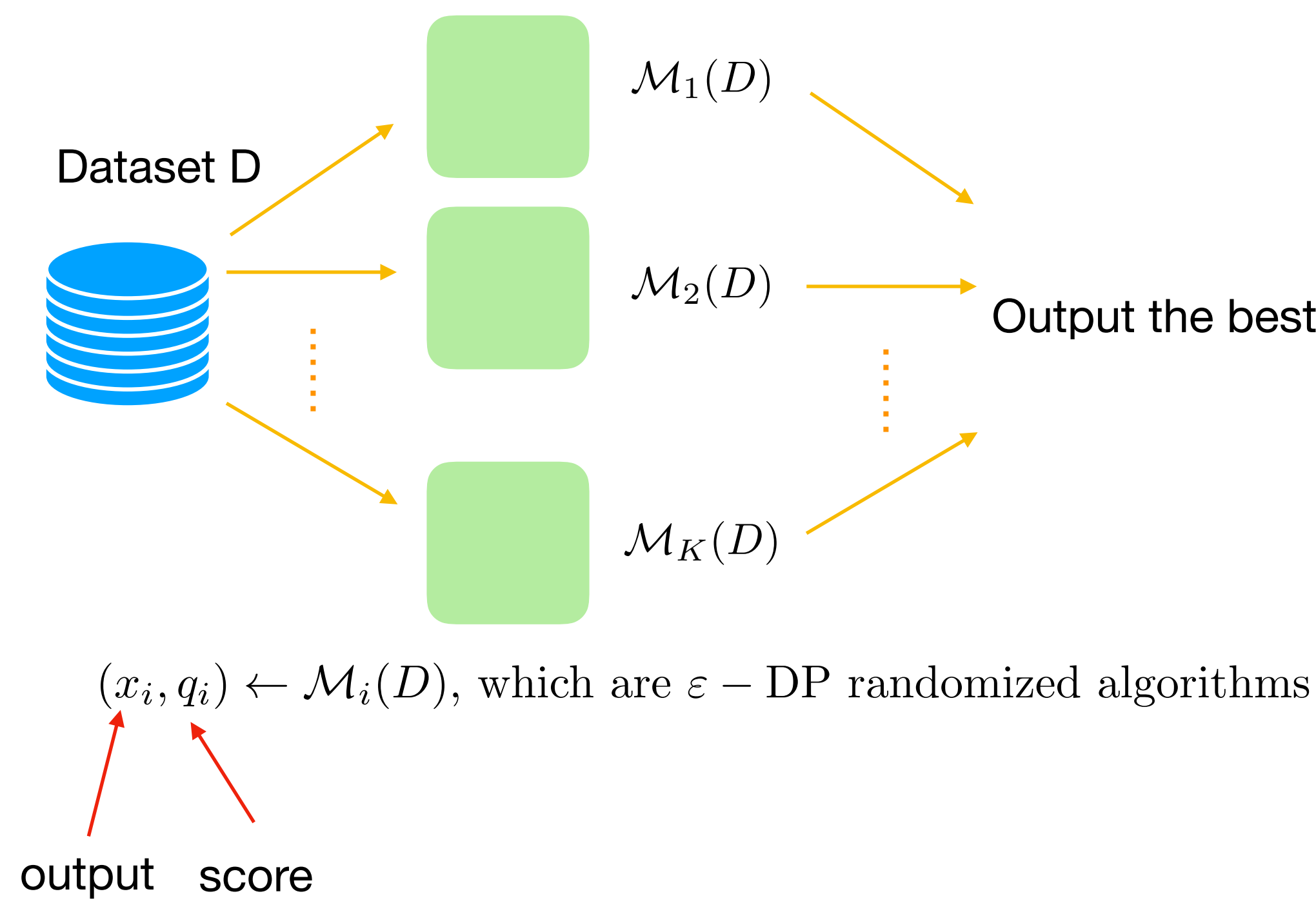
$$\Pr\left[q_j(D) \leq \max_i \{q_i(D)\} - \frac{1}{\epsilon} \ln \frac{K}{\delta}\right] \leq \delta$$

Utility

An example:



Private Candidates



Some *real* examples

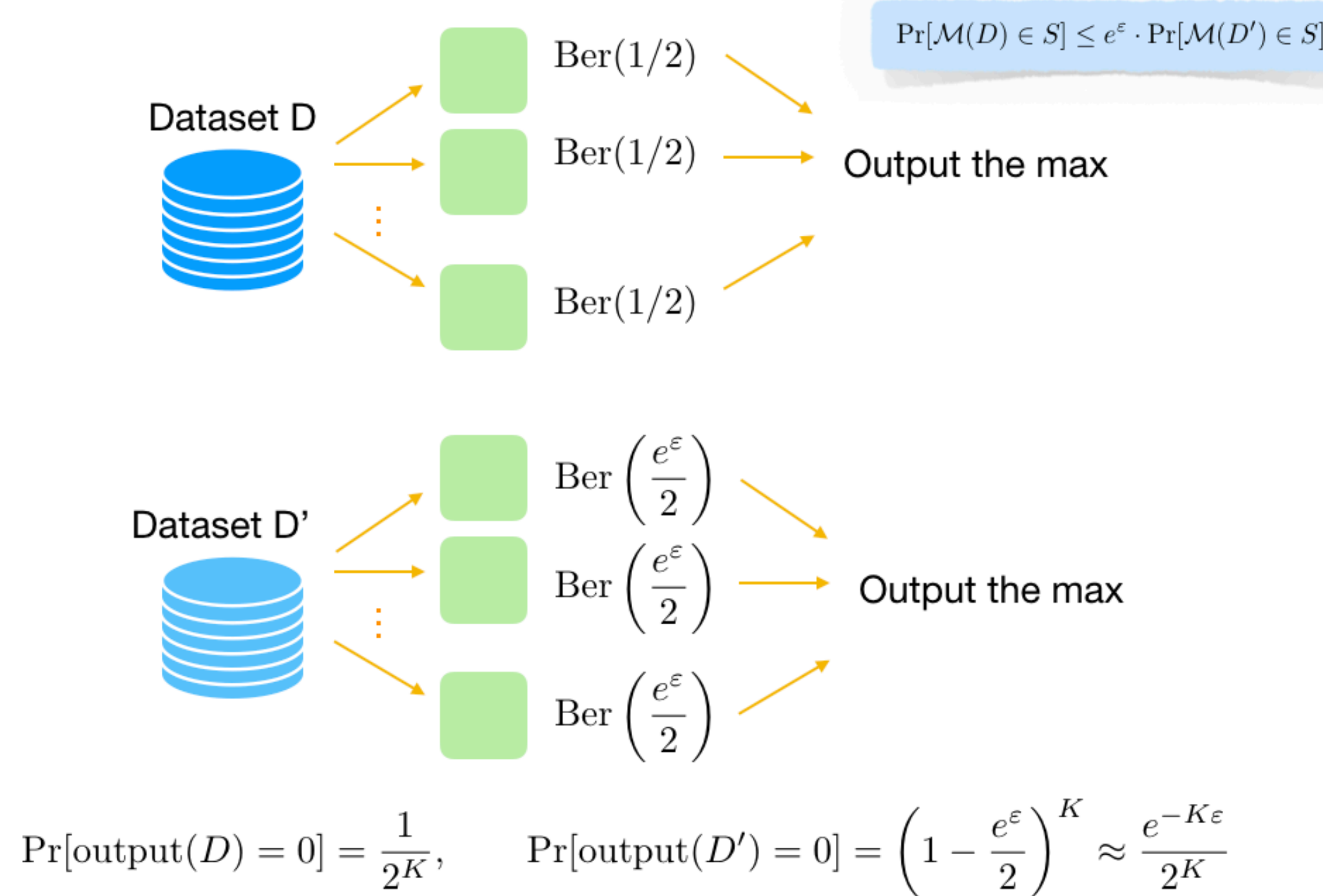
- Algorithm selection
- Model selection
- Neural network architecture
- Hyperparameters selection
-

Private Selection: Naive Attempt #1

Since $\forall i, \mathcal{M}_i(D)$ is ϵ -DP, what if we choose $\max_i \mathcal{M}_i$?

Basic composition: $(K\epsilon)$ -DP

Tight example for attempt #1

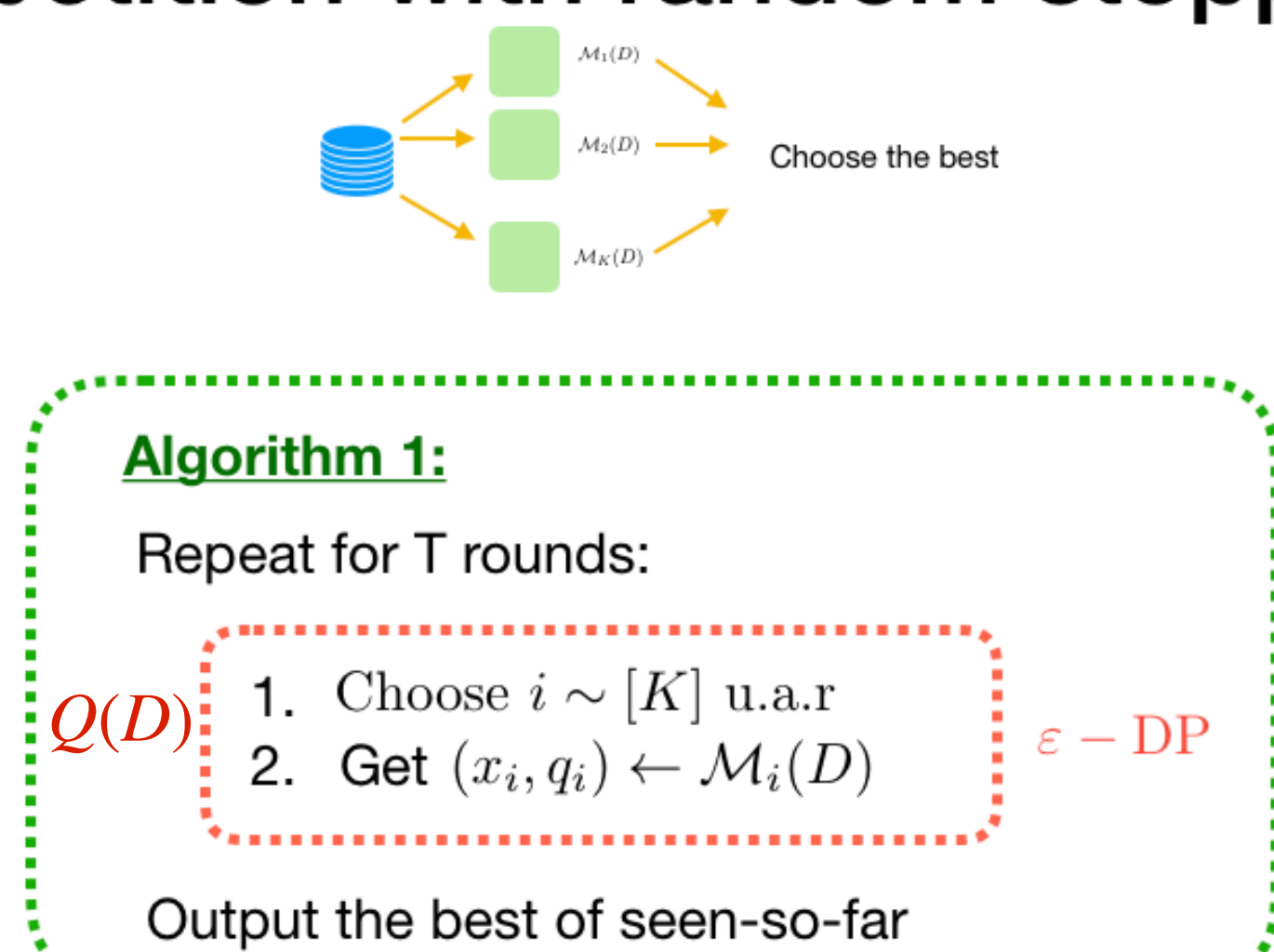


Private Selection: Naive Attempt #2

Since $\forall i, \mathcal{M}_i(D)$ is ϵ -DP, what if we choose $i \sim [K]$ u.a.r?

Indeed we do get ϵ -DP, but the probability of getting the best can be $\frac{1}{K}$

Repetition with random stopping



- For every fixed T, **Algorithm 1** is $(T\epsilon)$ -DP
- Our result: if $T \sim \text{Geom}(\cdot)$, then **Algorithm 1** is (3ϵ) -DP

Remarks

- Generalizes 1-Lipschitz queries
- For a suitable choice of $\text{Geom}(\cdot)$, can match the utility of the Exp. Mech.

Prior work

- Assume **Lipschitzness**: Exponential mechanism [McSherry, Talwar' 07]
- Assume **"local" Lipschitzness** [Raskhodnikova, Smith' 16]
- Assume a known **"good" target** [Gupta, Ligett, McSherry, Roth, Talwar' 10]

We are able to improve upon privacy, utility, and computational (sampling) efficiency

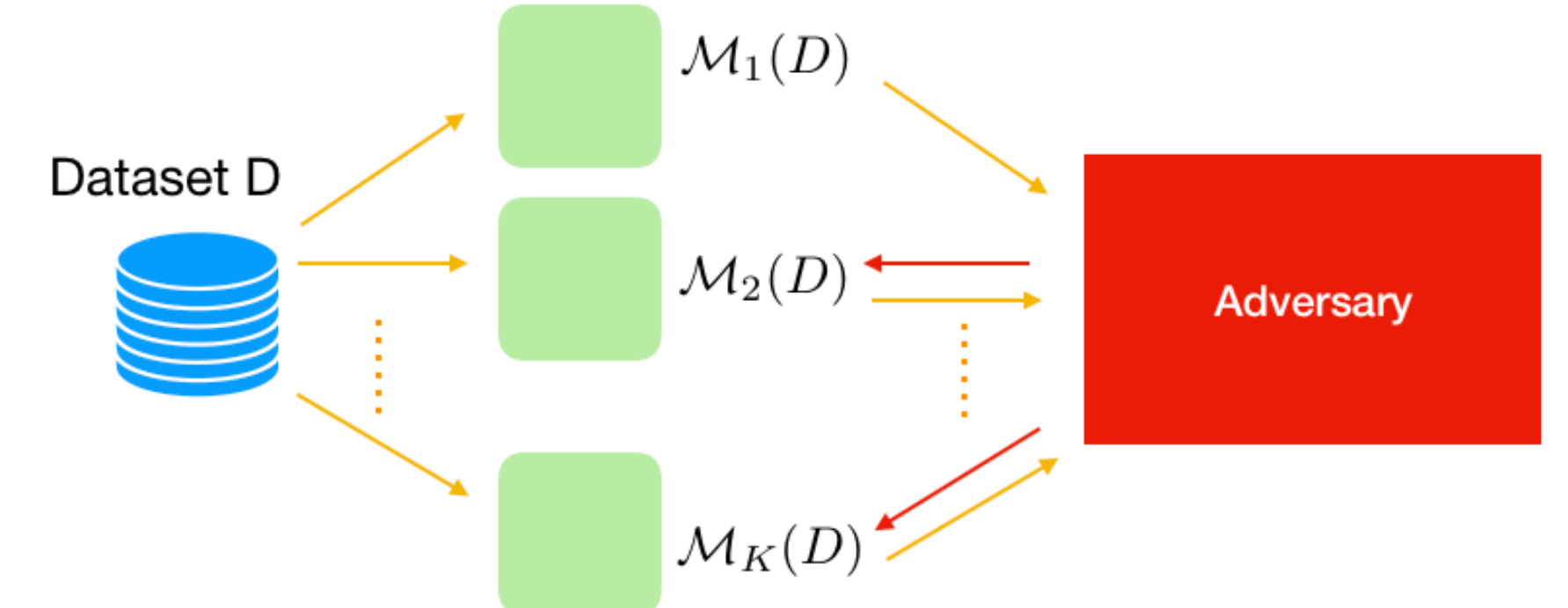
Utility for random stopping

Fix any constants $\alpha \in (0, 1)$, $\eta \in (0, 1/5)$, and choose $\gamma = \frac{4\alpha\eta}{5\ln 1/\eta}$ in Algorithm 1. If there is a threshold τ (unknown to the algorithm), and an event \mathcal{G} (on the output of Q) such that

$$\Pr_{\tilde{q} \sim Q(D)}[\tilde{q} \geq \tau] \geq \alpha,$$
$$\Pr_{\tilde{q} \sim Q(D)}[\tilde{q} \geq \tau \wedge \bar{\mathcal{G}}] \leq \frac{\alpha\eta^2}{\ln^2 \frac{1}{\eta}}.$$

Let $A_{\text{out}}(D)$ be the output of Algorithm 1 on D . Then, we have $\Pr[A_{\text{out}}(D) \in \mathcal{G}] \geq 1 - 5\eta$.

Adaptive Private Selection



Actually, life is about **adaptive** choices....

Indeed, there is an adaptive version of the Exp. Mech.:

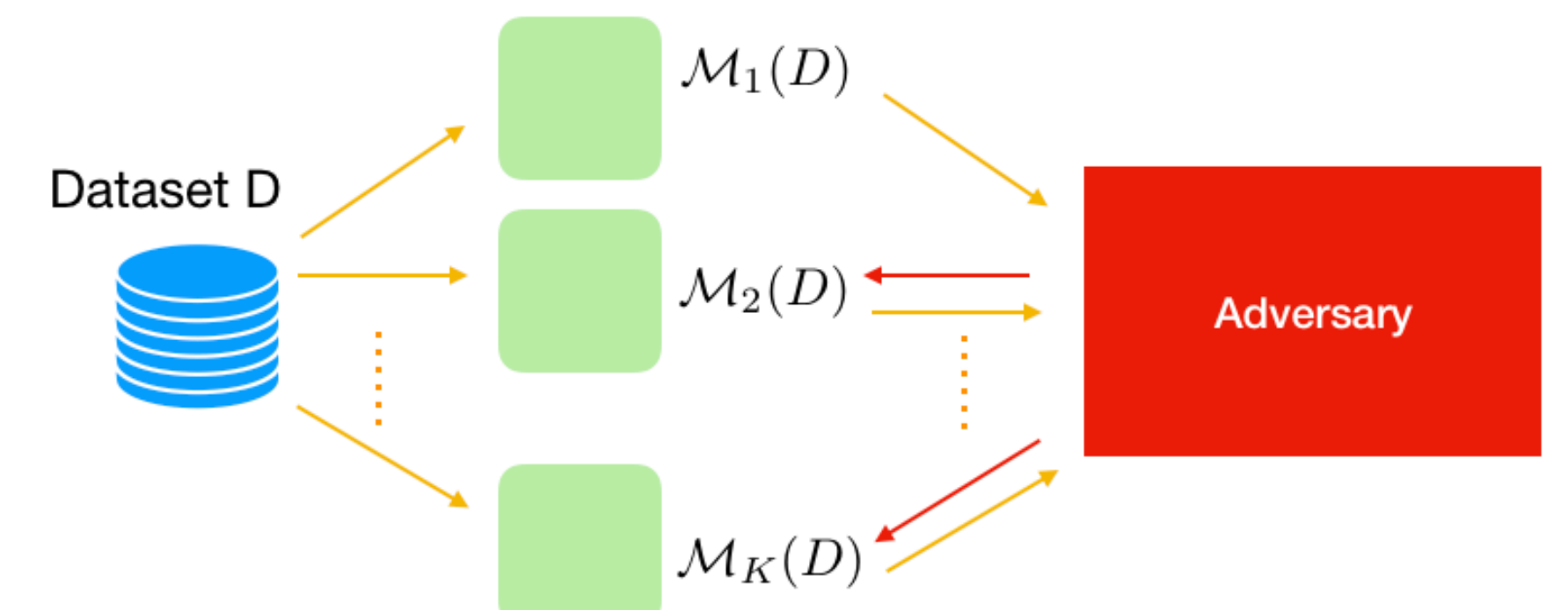
- the sparse vector algorithm
- due to Dwork, Naor, Reingold, Rothblum, and Vadhan '09

Motivating Applications

- Adaptive tuning in machine learning
- Adaptive data analysis: garden of forking paths. [Dwork, Feldman, Hardt, Pitassi, Reingold, and Roth' 15]
- ...

Sparse vector algorithm only works for Lipschitz queries. Can we go beyond Lipschitz queries?

Adaptive Private Selection



- Allow **adaptive** queries: $\mathcal{M}_i(D)$ are ϵ -DP randomized algorithms
- But only **threshold** queries

Median score

$$\text{Median}(\mathcal{M}_i(D)) := \sup \left\{ \tau : \Pr_{(\tilde{x}, \tilde{q}) \sim \mathcal{M}_i(D)}[\tilde{q} \geq \tau] \geq \frac{1}{2} \right\}.$$

Given a threshold τ

Goal: output the first i such that $\text{Median}(\mathcal{M}_i(D)) \geq \tau$.

Our Result for Adaptive Private Selection:

- There is an (ϵ, δ) -DP algorithm such that w.h.p.
- If a query is above the threshold, then Alg. reports "AboveThreshold"
- If Alg. reports i -th query is "AboveThreshold", then the i -th query is not "too much below the threshold" in terms of the "percentile-score"

Effectively, there is a reasonable probability of exceeding the threshold

Our approach:

- Introduce "percentile-score", which generalizes the median score
- Estimating & testing the "percentile-score" differentially privately
- Bound a variant of Earth mover's distance between sums of Bernoullis.

Open Problems & future work:

- Other stopping time distribution?
- DP preserving mechanism for more sophisticated (hyperparameter) optimization algorithm